

## TECHNICAL INFORMATION:

<b>PRODUCT:</b>	<b>A--LAS-CON-sensor-control-unit</b>	Date:	31.01.2006
	<i>Software - state: V1.2</i>		(wk)
<b>TOPIC:</b>	RS232-Interface-Protocol for A-LAS-CON- sensor-control-unit PC-Software-Version A-LAS-CON-Scope V1.2		

### RS232 Interface-Protocol PC ⇔ A-LAS-CON unit

- Standard RS232 serial interface, no hardware handshake
- 3-wire connection: GND, TX0, RX0
- Speed: 19200 baud, 8 data-bits, no parity-bit, 1 stop-bit, binary-mode

The control device (PC or PLC) have to send a frame of 18-words (1 word = 2 byte = 16 bit) to the A-LAS-CONTROL hardware. All words must be transmitted in binary format. The most significant byte must be transmitted first (MSB-first).

#### METHOD:

The microcontroller of the A-LAS-CONTROL unit is permanently reading (polling) the input-buffer of the RS-232 module. If the incoming word = **0x0055** (0x55 hexadecimal = **85** decimal), this is interpreted as the synchronisation-event **<sync-word>**. After this, the 2. word with the order number **<order-word>** is read in by the microcontroller.

The order word **<order-word>**, is followed by 16 further words **<parameter-word>**.

After reading the complete data-frame (18-words = 36 bytes), the A-LAS-CON unit executes the order which is coded at the 2.word **<order-word>**.

### Format of the parameter-frame:

Word No.	Meaning	Comment
1	<b>&lt;sync-word&gt;</b> = 0x0055	hex-code 0x0055, binary=00000000 01010101, dez.=85
2	<b>&lt;order-word&gt;</b>	Order word (c.f. table below)
3	parameter POWER	Laser Intensity (0 ... 1000) at transmitter
4	parameter REFERENCE	Teach-value (1 ...1000)
5	parameter TOLERANCE	Tolerance-value (1 ...1000), trigger-value for EVALMODE:DIFF
6	parameter HYSTERESIS	Hysteresis-value (for tolerance-window) (0 .. 130)
7	parameter POLARITY	Polarity setting for OUT0,OUT1 (0=DIRECT, 1=INVERSE)
8	parameter HOLD	Hold-time for OUT0,OUT1 (10,20,50,100,200,500,100,65535)
9	parameter HWMODE	Hardware-Mode ( 0:Disable All, 1:Enable All, 2:Enable Button, 3: Enable Potentiometer )
10	parameter AVERAGE	Average-value ( 1,2,4,8,16,32,64,128,256,512,1024 or 2048)
11	parameter EVALMODE	Evaluation-Mode (0:RAW-A, 1:A/Amax, 2:DIFF)
12	parameter MAXMODE	Unload actual maxima (0:off, 1:on)
13	parameter TRGLEVEL	Trigger-level for internal trigger
14	parameter TRGMODE	Trigger-mode (0:CONT, 1:INTERN, 2:EXT/HI, 3:EXT/LO)
15	parameter SDELAY	Scan-delay ( 6=10ms, 27=10ms, 210=50ms, 470=100ms, ... )
16	parameter DBUFLEN	Length of differential-buffer (new-values) (1,2,4,8,16,32,64)
17	parameter ANAMODE	Analog output mode ( 0=DIRECT 0..10V, 1=DIFFERENTIAL )
18	Parameter FREE	Parameter not used ( default=0 )

Meaning of the 2 <sup>nd</sup> word of the data-frame: <order-word>	
Value	Meaning / Action
0	Nop
1	Send parameter from PC into RAM of A-LAS-CON
2	Get A-LAS-RAM-parameter
3	Send parameter from PC into EEPROM of A-LAS
4	Get EEPROM parameters of A-LAS
5	Echo check: Get echo of A-LAS, line ok = 0xAA
6	Activate Teach at A-LAS-CON, store in RAM
7	Get software version info from A-LAS-CON
8	<b>Get measured values out of A-LAS-CON-RAM</b>
9	Get data-buffer-block out of A-LAS-CON-RAM,

### EXAMPLES:

Echo check <order-word>=5	
<order-word> = 5	
Echo check: send echo 0xAA in 3rd. word to PC	
DATA FRAME: PC → SENSOR	(18-Words=36Bytes, MSB first)
<order-word>=7 <sync.-word>	18
DATA FRAME: SENSOR → PC (18-Words=36Byte, MSB first)	
1      2      3. 0x55 5 0xAA 0 0 0 ... 0 0 0	18

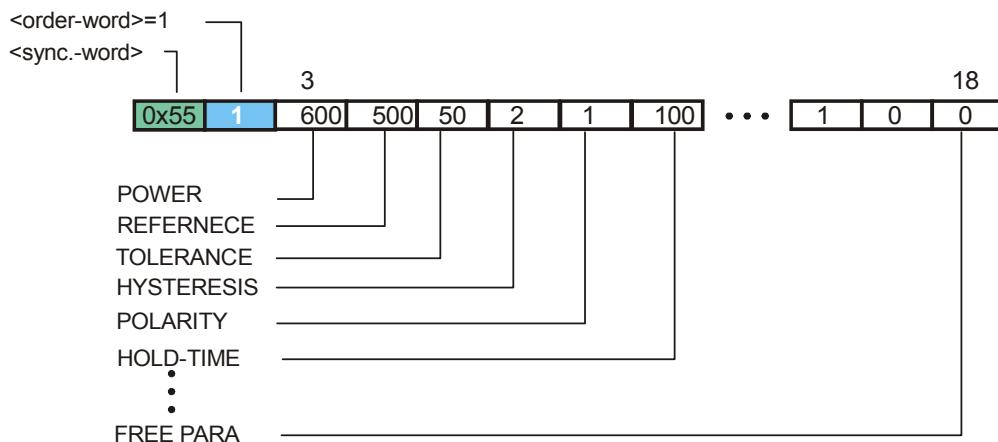
### SEND parameter to A-LAS-CON-RAM <order-word>=1

<order-word> = 1

Send actual parameters and store the frame into L-LAS-RAM.

**No data frame is send back to the PC after the parameter frame is read in !!!**

DATA FRAME: PC → SENSOR (18-Words=36Bytes, MSB first)

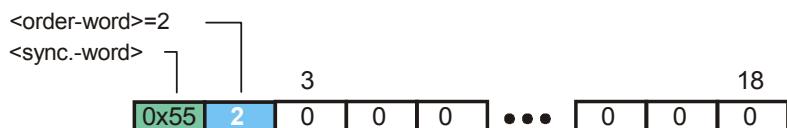


### GET A-LAS-CON-RAM parameter <order-word>=2

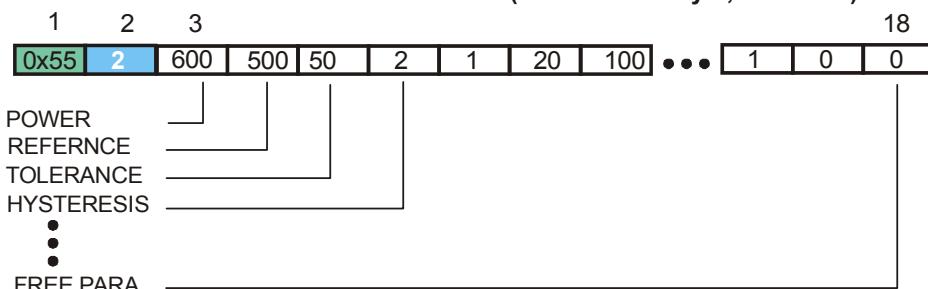
<order-word> = 2

GET A-LAS-CON-RAM parameter

DATA FRAME: PC → SENSOR (18-Words=36Bytes, MSB first)



DATA FRAME: SENSOR → PC (18-Words=36Byte, MSB first)



### GET measured-values of A-LAS-CON unit <order-word>=8

<order-word> = 8

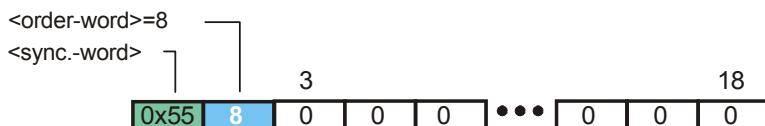
The A-LAS-CON-unit sends the actual measured values to the PC.

The 3. word is the actual measurement value **NORM**

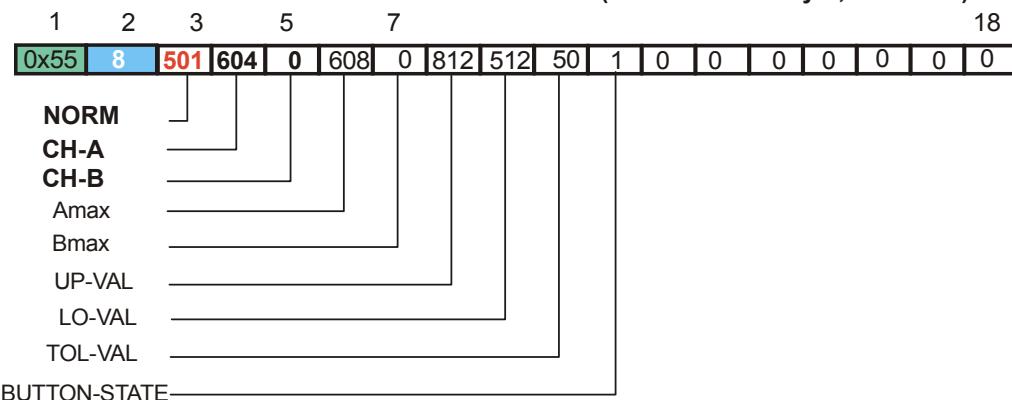
The 4. word is the raw-value of channel : **CH-A**

The 5. word of the raw-value of channel: **CH-B**

DATA FRAME: PC → SENSOR (18-Words = 36 Bytes, MSB first)



DATA FRAME: SENSOR → PC (18-Words = 36 Byte, MSB first)



NORM	:= measurement value of A-LAS-CON-unit
CH-A	:= raw-value of channel CHA
CH-B	:= raw-value of channel CHB (actually not used)
Amax	:= actual maximum value of CHA
Bmax	:= actual maximum value of CHB (actually not used)
UP-VAL	:= highest value in evaluated data curve after trigger-event
LO-VAL	:= lowest value in evaluated data curve after trigger-event
TOL-VAL	:= actual tolerance value (potentiometer – settings-value if enabled)
BUTTON-STATE	:= actual hardware-button-state